

DESIGN OF CONSTRAINT LECTURE

Design of constraints in precision systems

Background

- ⊙ History
- ⊙ Reasons
- ⊙ Requirements
- ⊙ Problems

Classes of Constraint

- ⊙ Kinematic
- ⊙ Quasi-Kinematic
- ⊙ Variable Geometry
- ⊙ Partial/Compliance

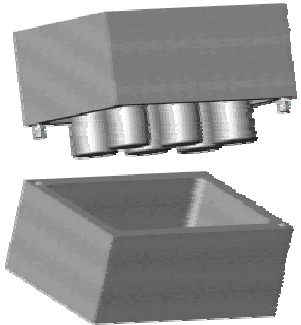
Hardware/discussion time

Elastic Averaging will be done next lecture

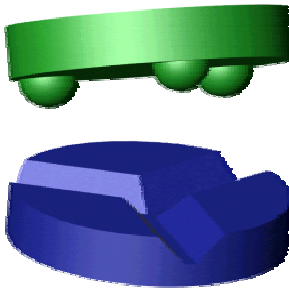
Common coupling methods



Elastic Averaging
Non-Deterministic



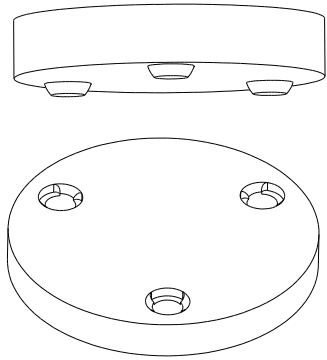
Pinned Joints
No Unique Position



Kinematic Couplings
Kinematic Constraint



Flexural Kin. Couplings
Kinematic Constraint



Quasi-Kinematic Couplings
Near Kinematic Constraint

	0.01 μm	0.10 μm	1.0 μm	10 μm	100 μm
Pinned Joints				[Blue bar from 10 to 100 μm]	
Flexural Kinematic Couplings			[Blue bar from 1.0 to 100 μm]		
Elastic Averaging			[Blue bar from 1.0 to 100 μm]		
Quasi-Kinematic Couplings		[Blue bar from 0.10 to 100 μm]			
Kinematic Couplings	[Blue bar from 0.01 to 100 μm]				

Perspective: What the coupling designer faces...

APPLICATION

Fiber Optics

Optical Resonators

Large array telescopes

Automotive

SYSTEM SIZE

Meso

Meso

60 ft diam.

3 ft

REQ'D PRECISION

Nano

Nano

Angstrom

1 micron

Problems due to strain affects

- ⊙ Thermal Affects Air, hands, sunlight
- ⊙ Gravity Sagging
- ⊙ Stress Relief Time variable assemblies
- ⊙ Loads Stiffness

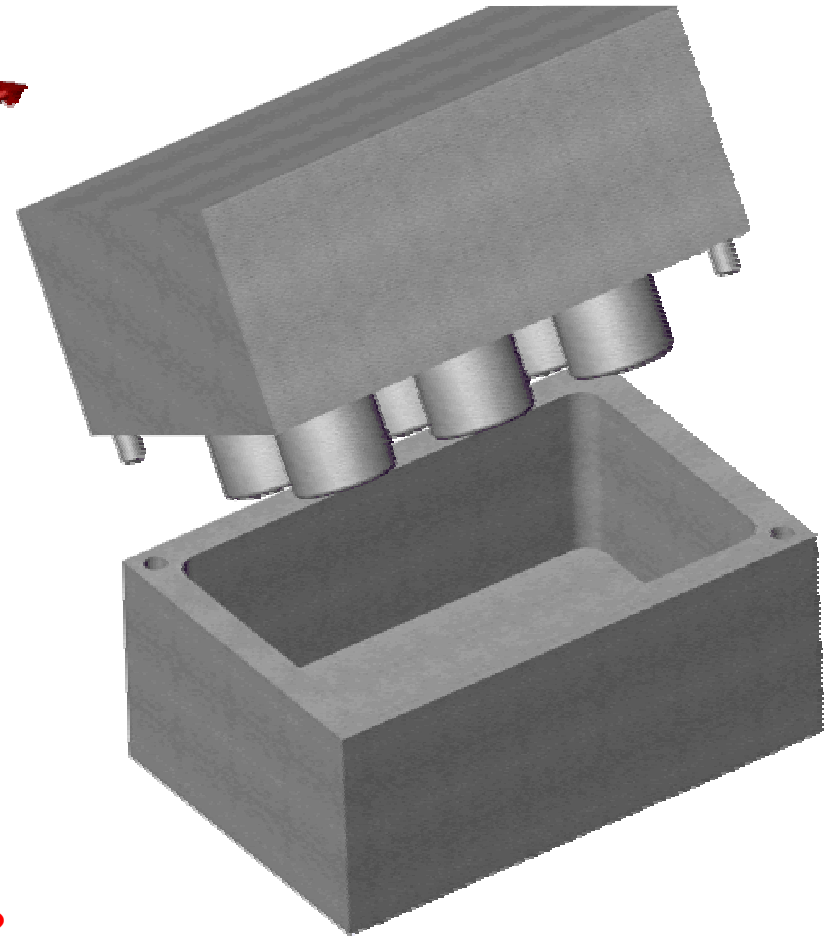
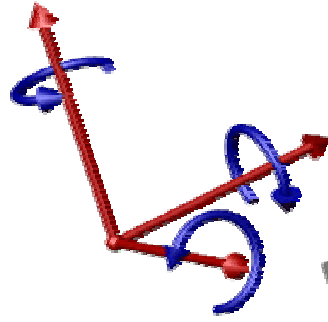
Problems due to sub-optimal designers

- ⊙ Competing cost vs performance
- ⊙ Automotive (no temperature control, large parts, resistance to change)

General service requirements & applications

Ideal couplings:

- ⊙ Inexpensive
- ⊙ Accurate & Repeatable
- ⊙ High Stiffness
- ⊙ Handle Load Capacity
- ⊙ Sealing Interfaces
- ⊙ Well Damping



Example Applications:

- ⊙ Grinding
- ⊙ Optic Mounts
- ⊙ Robotics
- ⊙ Automotive

Sensitivity

- ⊙ **What are the sensitive directions?!?!?!?!?**

Couplings are designed as systems

You must know what is going on (loads, environment, thermal)!

Shoot for determinism or it will “suck to be you”

